

AMENDMENTS TO THE CLAIMS:

This listing of claims will replace all prior versions, and listings of claims in the application:

LISTING OF CLAIMS:

Claims 1-10 (cancelled)

11. (New) A navigation apparatus comprising:

a deviation judging unit configured to judge whether a moving object has deviated from a guided route to a destination;

a distance calculating unit configured to calculate a distance from a deviated point to a planned route point when the deviation judging unit judges that the moving object has deviated from the guided route before passing through the planned route point;

a route judging unit configured to judge whether to pass the planned route point based on the distance; and

a re-searching unit configured to re-search a route based on a result of judgment by the route judging unit.

12. (New) The navigation apparatus according to claim 11, wherein

the distance calculating unit is configured to calculate the distance for predetermined times as the moving object moves off the guided route, and

the route judging unit is configured to judge that the planned route point is not to be passed when the distance calculated for the predetermined times is an increasing trend.

13. (New) The navigation apparatus according to claim 11, wherein

The guided route includes a first planned route point to be guided first, and a second planned route point to be guided

following the first planned route point,

the distance calculating unit is configured to calculate a first distance and a second distance, the first distance being a distance from the deviated point to the first planned route point, the second distance being a linear distance from the deviated point to the second planned route point, when the deviation judging unit judges that the moving object has deviated from the guided route before passing the first planned route point, and

the route judging unit is configured to judge whether to pass the first planned route point based on the first distance and the second distance.

14. (New) The navigation apparatus according to claim 13, wherein

the distance calculating unit is configured to calculate the first distance and the second distance for predetermined times as the moving object moves off the guided route, and

the route judging unit is configured to judge that the first planned route point is not to be passed when the first distance calculated for the predetermined times is an increasing tend and the second distance calculated for the predetermined times is a decreasing tend, and

the re-searching unit is configured to re-search a route passing the second planned route point without passing the first planned route point.

15. (New) The navigation apparatus according to claim 11, further comprising a presenting unit configured to present, when the route judging unit judges that the planned route point is not to be passed, that the planned route point is not to be passed.

16. (New) The navigation apparatus according to claim 11, further comprising:

a presenting unit configured to present a content to confirm whether to pass the planned route point when the route judging unit judges that the planned route point is not to be passed; and

an acquiring unit configured to acquire information indicative of an instruction in response to the confirmation, wherein

the re-searching unit configured to re-search a route based on the instruction.

17. (New) The navigation apparatus according to claim 11, wherein the route judging unit is configured to judge that the planned route point is to be passed when the distance is larger than a threshold.

18. (New) A route searching method comprising:

judging whether a moving object has deviated from a guided route to a destination;

calculating a distance from a deviated point to a planned route point when it is judged that the moving object has deviated from the guided route before passing through the planned route point at the judging;

judging whether to pass the planned route point based on the distance; and

re-searching a route based on a result of judgment at the judging whether to pass the planned route point.

19. (New) The route searching method according to claim 18, wherein

the calculating includes calculating the distance for predetermined times as the moving object moves off the guided route, and

the judging whether to pass the planned route point includes judging that the planned route point is not to be passed when the distance calculated for the predetermined times is an increasing

trend.

20. (New) The route searching method according to claim 18, wherein

The guided route includes a first planned route point to be guided first and a second planned route point to be guided following the first planned route point,

the calculating includes calculating a first distance and a second distance, the first distance being a distance from the deviated point to the first planned route point, the second distance being a linear distance from the deviated point to the second planned route point, when the moving object is judged to be deviated from the guided route before passing the first planned route point at the judging whether a moving object has deviated, and

the judging whether to pass the planned route point includes judging whether to pass the first planned route point based on the first distance and the second distance.

21. (New) The route searching method according to claim 20, wherein

the calculating includes calculating the first distance and the second distance for predetermined times as the moving object moves off the guided route, and

the judging whether to pass the planned route point includes judging that the first planned route point is not to be passed when the first distance calculated for the predetermined times is an increasing tend and the second distance calculated for the predetermined times is a decreasing tend, and

the re-searching includes re-searching a route passing the second planned route point without passing the first planned route point.

22. (New) The route searching method according to claim 18,

further comprising presenting, when it is judged that the planned route point is not to be passed at the judging whether to pass the planned route point, that the planned route point is not to be passed.

23. (New) The route searching unit according to claim 18, further comprising:

presenting a content to confirm whether to pass the planned route point when it is judged that the planned route point is not to be passed at the judging whether to pass the planned route point; and

acquiring information indicative of an instruction in response to the confirmation, wherein

the re-searching includes re-searching a route based on the instruction.

24. (New) The route searching method according to claim 18, wherein the judging whether to pass the planned route point includes judging that the planned route point is to be passed when the distance is larger than a threshold.

25. (New) A computer-readable recording medium that stores therein a route searching program making a computer execute:

judging whether a moving object has deviated from a guided route to a destination;

calculating a distance from a deviated point to a planned route point when it is judged that the moving object has deviated from the guided route before passing through the planned route point at the judging;

judging whether to pass the planned route point based on the distance; and

re-searching a route based on a result of judgment at the judging whether to pass the planned route point.